

Fig. 7. Drift Chamber region with data; red hits will be removed by noise removal

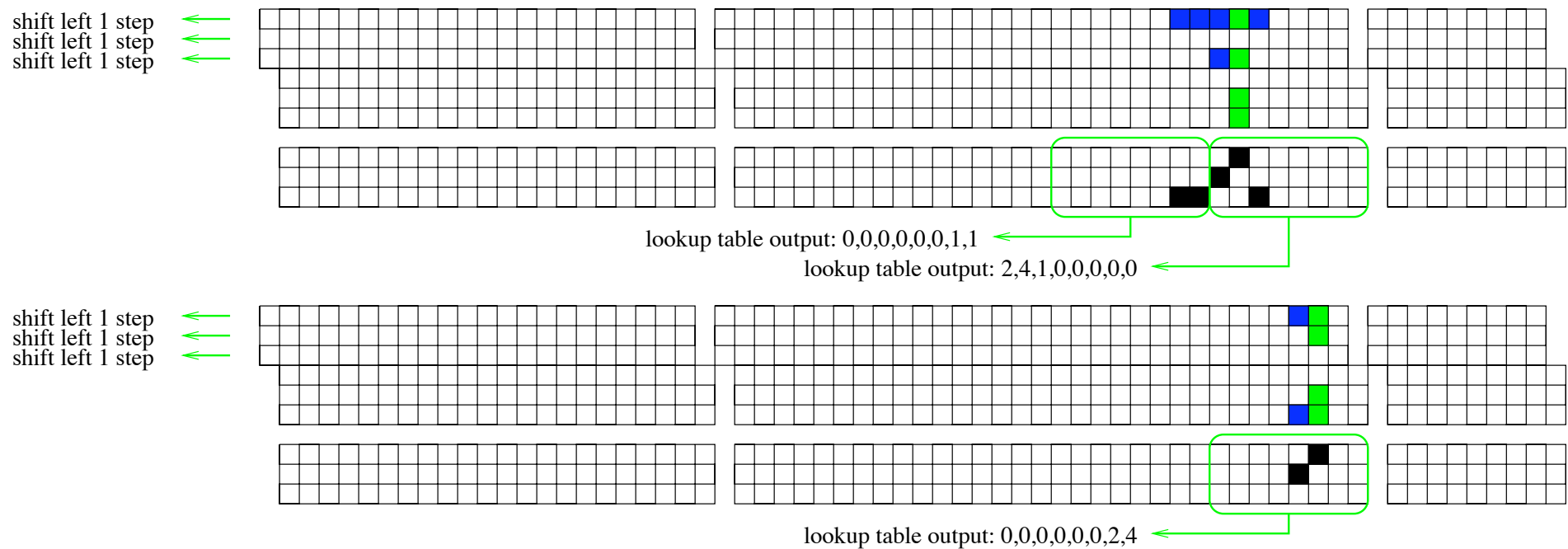


Fig. 8. Segment search in superlayers: layer shifts, superlayer sums, lookup table